



INTERNATIONAL APPLICATION PUBLISHED UNDER THE PATENT COOPERATION TREATY (PCT)

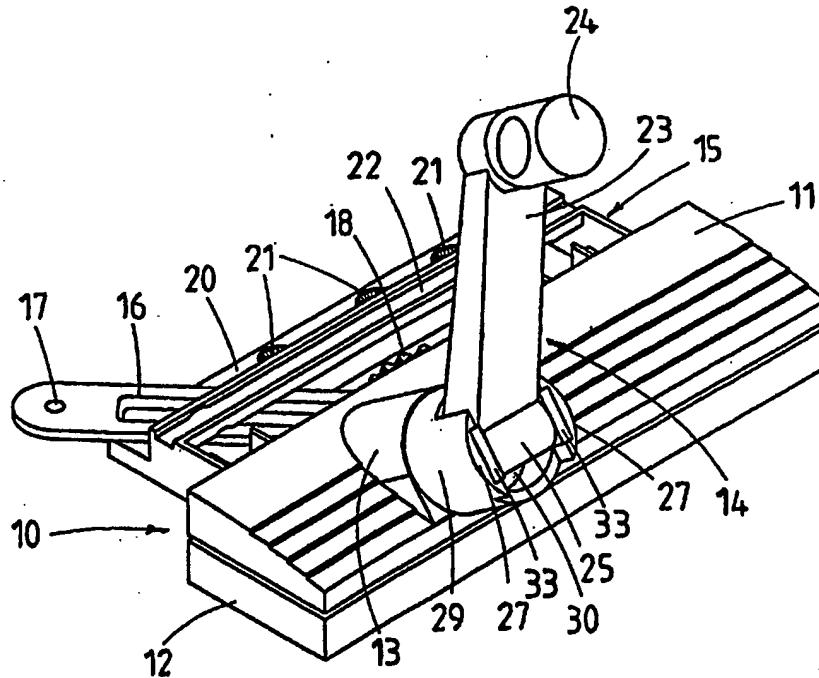
(51) International Patent Classification 6 :	A1	(11) International Publication Number: WO 95/18284
E05F 11/10, 11/34		(43) International Publication Date: 6 July 1995 (06.07.95)

(21) International Application Number: PCT/NZ94/00150	(81) Designated States: AM, AT, AU, BB, BG, BR, BY, CA, CH, CN, CZ, DE, DK, EE, ES, FI, GB, GE, HU, JP, KE, KG, KP, KR, KZ, LK, LR, LT, LU, LV, MD, MG, MN, MW, NL, NO, NZ, PL, PT, RO, RU, SD, SE, SI, SK, TJ, TT, UA, US, UZ, VN, European patent (AT, BE, CH, DE, DK, ES, FR, GB, GR, IE, IT, LU, MC, NL, PT, SE), OAPI patent (BF, BJ, CF, CG, CI, CM, GA, GN, ML, MR, NE, SN, TD, TG), ARIPO patent (KE, MW, SD, SZ).
(22) International Filing Date: 21 December 1994 (21.12.94)	
(30) Priority Data:	
250557 22 December 1993 (22.12.93) NZ 264431 8 September 1994 (08.09.94) NZ	
(71) Applicant (for all designated States except US): INTERLOCK INDUSTRIES LIMITED [NZ/NZ]; Portsmouth Road, Miramar, Wellington 6003 (NZ).	Published With international search report. Before the expiration of the time limit for amending the claims and to be republished in the event of the receipt of amendments.
(72) Inventor; and	
(75) Inventor/Applicant (for US only): TAYLOR, Nigel, Alan, Colebrooke [NZ/NZ]; 21 Roseneath Terrace, Roseneath, Wellington 6001 (NZ).	
(74) Agents: HOPKINS, Donald, Leslie et al.; Unit 2, Northcote Office Park, 145 Queen Street, Palmerston North 5330 (NZ).	

(54) Title: A ROTARY WINDOW OPERATOR

(57) Abstract

A rotary window operator to effect opening and closing of a window. A rotatable handle (14) is mounted on a housing (10) from which a link member (16) projects. The handle (14) is pivotally coupled to a cage (29) in which a bush (30) is slidably engaged. A cam surface (25) of handle (14) forces teeth on bush (30) to engage with teeth of cage (29) when the handle is pivoted from a non-use position to an in-use position. A drive shaft coupled to bush (30) has a gear which meshes with gear wheel (18) of link member (16) whereby rotation of the handle when in the in-use position imparts movement in link member (16).



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A ROTARY WINDOW OPERATOR

5 This invention relates to an operator for a window especially
a window of the casement type.

10 Window operators of a type having a linkage connected between
the window sash and window frame with the linkage being
actuated by a rotatable handle are known. Such operators
15 typically can include a housing with which the handle is
rotatably mounted. A gear mechanism couples a drive from the
handle to the linkage. Thus rotation of the handle causes
the linkage to move relative to the housing such that the
linkage pivots to thereby cause a window sash coupled to the
20 linkage to move to respective open or closed positions in the
window frame.

25 It is known to have the handle arranged such that it can be
moved into a parked or non-use position where it does not
project from the housing. This ability to move the handle
into a "parked" position reduces the possibility of someone
or something being snagged by or entangling with the handle.
It also improves the aesthetics of the operator when it is
not in use.

30 25 However, with known arrangements the handle must be rotated
to a prescribed position where it can be folded away into the
non-use position. In addition even when folded away the
handle remains coupled to the gear mechanism/linkage.

35 30 It is therefore one object of the present invention to
provide a rotary window operator whereby irrespective of the
angular position of the handle the handle can be moved into a
non-use position and disconnected from the drive
mechanism/linkage of the operator.

Broadly therefore in one aspect of the invention there is
provided a rotary window operator which includes a rotatable

handle drivingly coupled to a link member such that movement of the link member to effect opening and closing of a window is achieved by rotation of the handle, the handle being movable into a non-use position whereupon coupling means 5 providing the drive coupling between the handle and the link member is disconnected, the coupling means permitting the handle to be movable into the non-use position at any angular disposition of the handle.

10 Known window operators also suffer from somewhat fiddley and time consuming installation requirements. This usually arises because the mounting arrangement includes a number of separate components which the installer must manipulate and support during the installation procedure.

15 Accordingly a further object of the present invention is to provide a rotary window operator which is straight forward and convenient to install in a window frame.

20 Broadly in a second aspect of the invention there is provided a rotary window operator which includes a housing from which a mounting projects said mounting being engageable through an opening in a window frame, said mounting incorporating at least one clamping element, the clamping element being 25 located in a first position which does not hinder the insertion of the mounting through said opening but is movable to a second position whereby it can engage with part of the frame defining the opening and thereby restrict retraction of the mounting through said opening.

30 In the following more detailed description of the invention reference will be made to the accompanying drawings in which:-

35 Figure 1 is a perspective view of the rotary window operator according to one embodiment,

Figure 2 is a plan view of the operator as shown in Figure 1,

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Figure 3 is a detail illustration of the handle when in the operative position,

Figure 4 is a detailed view of the handle when moved to the non-use position,

5 Figure 5 is a perspective view of a drive gear wheel mounted with the link member,

Figure 6 is a similar view to Figure 5 showing the gear wheel fixedly attached to the link member,

10 Figure 7 is a plan view of the operator showing in detail a means whereby the housing thereof can be mounted to a window frame,

Figure 8 is an end section view taken on line A-A of Figure 7 and showing a window frame associated with the operator,

15 Figure 9 is a perspective view of the operator showing the mounting arrangement illustrated in Figures 7 and 8, Figure 10 is a sectioned perspective view of the base of the housing,

20 Figure 11 is a perspective view of a further form of the operator,

Figure 12 is a perspective view of a series of screw fixing placement inserts for the operator, and

25 Figure 13 is a plan view showing the relative positions of the screw fixing placements when using the inserts of Figure 12.

The rotary window operator according to the embodiment as illustrated comprises a housing 10 formed by a cover 11 and a base 12. A turret 13 projects from the upper surface of cover 11 and rotatably mounted therewith is a handle assembly 14. Projecting from housing 10 from one side edge thereof is a mounting frame 15.

30 Projecting out from the interior of housing 10 is a link arm 16. An opening 17 at the outer or free end of link arm 16 is pivotally attachable to a connecting link (not shown) extending from a window sash. The inner end of link arm 16 is coupled to a gear wheel 18.

A drive shaft 19 coupled with handle assembly 14 (as hereinafter described) carries a drive gear (not shown) which meshes with gear wheel 18. Accordingly as the handle assembly 14 is rotated drive is imparted to gear wheel 18 which in turn pivotally moves link arm 16 about the axis of rotation of gear wheel 18.

Link arm 16 moves over a land 20 formed as part of frame 15. 10 Openings 21 are formed in land 20 to facilitate mounting of the operator in a window frame as will be described later. Located above land 20 and parallel to but back toward housing 10 is a bridge 22. Thus effectively link arm 16 slidingly moves in an elongate slot defined by land 20 and bridge 22. 15 As a consequence of bridge 22 being immediately adjacent to link arm 16 any tendency of link arm 16 to buckle upon a force being applied to the window sash (this force being transmitted via the connector link) is largely prevented.

20 As shown in Figure 10 a sliding surface 52 is located below and spaced from bridge 11. The link arm 16 is located in sliding contact with surface 52. In the preferred form surface 52 is formed by an elongate block 53 of plastics material which is fitted into frame 15. To this end a pair 25 of tabs 54 projecting from block 53 engage in recesses 55 formed in the floor 56 of base 12. Likewise a pair of tabs (not shown) projecting from the other long edge of block 53 engage in recesses in the underside of land 20. Preferably the tabs, or at least one pair thereof are of an interference 30 fit in the respective recesses. Alternatively block 53 can be an interference fit in the area between land 20 and floor 56 where block 53 locates.

35 In an alternative arrangement the sliding surface 52 can be a layer of plastics material on say a metal substrate. In either case surface 52 ensures there is no sliding contact between arm 16 and a metal surface during normal operation of the operator.

The handle assembly 14 consists of a handle 23 with a rotatable knob 24 at the outer or free end thereof. The other or inner end of handle 23 incorporates a bulbous portion 25 through which a pivot pin 26 is engageable. This bulbous portion 25 engages between a pair of flanges 27. The pivot pin 26 is engaged at each end to a respective flange 27.

Engaged between bulbous portion 25 and each flange 27 is an insert 33 which is preferably made from plastics or other resilient material. An arcuate slot (not shown) is formed in each insert 33. A pin (also not shown) projecting from the side of bulbous portion 25 engages in the slot and is slidably movable therealong as the handle 23 moves about pivot pin 26. At each end of the arcuate slot is an enlarged portion which is equal to or slightly greater than the diameter of the pin. The width of the slot is, however, less than the diameter of the pin.

Due to the resilient nature of the material the slot expands as the pin moves therealong. The enlarged portions correspond with the two extreme end positions of the handle, ie. the in-use and non-use positions. The inserts 33 therefore act as detent plates which determine the end points of travel of the handle about pivot pin 26. Due to the constricted nature of the arcuate slot a slight resistance to movement of the pin therealong occurs so that a definite click into the enlarged portion indicates to the user that an end position has been achieved. As well the handle stays in such end position due to the inability of the pin to slide along the arcuate slot until a force is applied to the handle by the user.

The drive shaft 19 extends through a bore 28 in a cage 29 to drivingly engage with a bush 30. The bush 30 is located within cage 29 and a spring 31 engages between the floor of

cage 29 and a shoulder 32 of bush 30. Flanges 27 are formed as part of or are engaged with cage 29.

Opposing surfaces of cage 29 and bush 30 respectively are 5 formed with gear teeth 34 and 35. These gear teeth 34 and 35 can mesh when the handle is in the in use position (Figure 3) and are disengaged when the handle is folded or moved to the non-use position (Figure 4). Gear teeth 34 and 35 thus form a saw tooth clutch arrangement.

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With the handle 23 in the folded or non-use position the non meshing of gear teeth 34 and 35 result in the drive shaft 19 not being drivingly engaged with cage 29. Thus if the handle 15 23, when in the folded position, is rotated no drive is imparted to the drive shaft 19.

However, when handle 23 is pivoted about pivot pin 26 to the in use position, ie. in the direction of arrow B in Figure 3 the cam profile 25a formed by bulbous portion 25 imparts a 20 downward force on bush 30 against the bias of spring 31 so that teeth 34 and 35 mesh. As a consequence drive between the handle and drive shaft 19 is completed such that as the handle is rotated so too is drive shaft 19.

25 When the handle is moved in the direction of arrow C (Figure 4) bush 30 moves under the influence of spring 31 which causes gear teeth 34 and 35 to disengage.

As a result of the arrangement described above handle 23 can 30 be folded into the non-use position at any angular disposition of the handle relative to housing 10. When in the non-use position rotation of the handle does not result in any drive being imparted to the drive shaft 19. However, when handle 23 is folded back into the in use position the 35 immediate engagement of gear teeth 34 and 35 results in drive being once again reinstated.

Referring now to Figures 5 and 6, a novel means of connecting the gear wheel 18 to link arm 16 is shown. Typically with known rotary window operators the gear wheel is formed as part of the link arm. However, according to the present invention the link arm 16 is formed with an annular wall 36 within which a pivot pin (not shown) of housing 10 can engage. The link arm 16 is thus pivotal about the axis of the pivot pin when the handle is rotated. Formed from the parent metal of arm 16 are a plurality of lugs 37 which engage within openings 38 of gear wheel 18 (see Figure 5).

Openings 38 are countersunk so that the lugs 37 can be swagged outwardly as shown in Figure 6 to thereby capture gear wheel 18 onto link arm 16. This enables, for example, the link arm to be made of say stainless steel and the gear wheel 18 of say a sintered material or machined from a material more suitable for gear manufacture such as free machining mild steel.

The housing 10 is typically mounted to a window frame F (see Figure 8) by mounting frame 15 engaged through a suitably shaped opening broached in the frame (see detail illustration in Figure 8). In the mounted position the face surface 24 of housing 10 is in abutting contact with the inner face surface 42 of frame F.

Means are provided for drawing the face surface 41 into such abutting contact with surface 42. These means include a novel arrangement, as hereinafter described, which enables the operator housing 10 to be located with frame sections of various thickness within a limited range of, for example, from $\frac{1}{4}$ " to $\frac{3}{4}$ ".

The novel fixing means consists of a pair of washers 43 which are located in pockets 57 (see Figure 10) formed in frame 15. Pocket 58 is formed by a rebate in the edge of floor 56 and the opposing surface of block 53. Each washer is elongate

and incorporates a central opening 45 through which a threaded fastener 44 engages.

Washer 43 is located in pocket 57 on its side (see dotted detail in the enlargement of Figure 7) so that the mounting frame 15 can be pushed through the slot formed in the frame F. The opening 45 in washer 43 is of smaller diameter than the outside diameter of fastener 44. As a consequence rotation of fastener 44 about its longitudinal axis results in the washer being able to be rotated until it is vertically orientated and engages against a lug 47.

In such position the washer is prevented by lug 47 from further rotation and is aligned between a pair of spaced apart flanges or walls 48. Further rotation of fastener 44 (the threaded end of which is located in a threaded opening in cover 11) causes the washer 43 to move forwardly until it engages against a pair of diametrically opposed upstands 49 and 50 which extend along frame F parallel to the outer wall 20 of frame F which incorporates surface 42.

As a consequence surface 41 of housing 10 is drawn into engagement with surface 42 of frame F and the housing is thus clamped into position.

25 While the integral washers 43 provide for clamping in a horizontal plane they also allow for a degree of lateral adjustment of the housing relative to the frame F. As a consequence an installer can position the housing 10 and then 30 clamp it into position by screwing in both of the threaded fasteners 44 as described above.

Within a limited range the distance between the face 42 of frame F and the diametrically opposed projections 49 and 50 35 can vary. This variation is accommodated by the washer 43 being movable into clamping positions within the range shown in Figure 8 where the washer 43 is shown in dotted detail adjacent the diametrically opposed projecting walls 49 and 50

(also shown in dotted detail) at one extreme of a thicker frame section and the walls 49 and 50 shown in full at the other extreme (ie. thinner frame section).

5 To facilitate fixing of the housing 10 in place fasteners are engaged through openings 21 of frame 15 and into the window frame F. A packer or packers 58 (see Figure 10) is located beneath land 10 and the adjacent portion of frame F. Preferably the packer 58 has a small rib 59 at each end 10 thereof which engages against the side of frame 15 so as to locate the packer in position. Also the packer is so dimensioned that a gap 60 remains between the packer and wall 49. This gap leaves a clear channel should any water or moisture get in behind the packer 58.

15 Thus in contrast to known rotary window operators installation of the operator according to the present invention is straight forward and easy to carry out. As described above the integral washers provide a simple means 20 of clamping the housing in position and make allowance for variations in frame thickness. It is then a simple matter of applying the fixings through openings 21 in land 20 to complete fixing of the housing 10 in the frame F.

25 In addition the overall top to bottom height of the mounting frame 15 is such that the opening broached in the frame can be located above the adjacent horizontal surface of the sill of the frame. As a consequence any water or moisture gaining access behind the packer 58 is not able to enter into the 30 opening broached in the frame and therefore to the internal surfaces of the frame F. The aforementioned gap 60 between the packer 58 and the wall 49 of the frame F also ensures that no water build up occurs which could lead to water entering through the opening in the frame.

The operator according to the present invention is open to modification. A further form of the invention is, for example, shown in Figure 11. In this form of the operator

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the bridge 22 is of a different configuration, but more particularly the operator includes the additional features of an adjustable connection 61 provided with link arm 62 and a screw fixing placement insert for mounting of the operator in 5 a window construction.

In Figure 11 there is shown a link arm 62 which is connected via a pivot joint 63 to operator arm 16. The pivot joint 63 can be of the type described in, for example, British patent 10 specification No 2237059. Likewise a mounting base 64 is pivotally coupled via a further pivot 65 (which in the preferred form is of the type used at pivot 63) to link arm 62. An L shaped bracket 66 is mountable to the mounting base 65. This mounting bracket 66 has a pair of openings 67 15 whereby the bracket can be fixedly coupled by screws (not shown) to a window sash.

Bracket 66 and the mounting base 64 are also coupled to the sash by way of screws that locate through elongate openings 20 72 in base 64 and round holes 68 in the mounting bracket 66. If the installation is correct then the assembly can be fixed by a countersunk head screw through the bearing 65 and corresponding slotted hole 69 in the bracket 66.

25 If, however, adjustment is required the two screws that locate through openings 68 can be backed off, but not removed, and the base 64 moved forwards or backwards and re-engaged by serrations 70 engaging with serrations 71 of the mounting bracket 64. Once this alignment is achieved the 30 assembly is completed by fixing a countersunk screw through the elongate opening in the mounting bracket 64 through the bearing 65.

35 This adjustable fixing permits a lateral adjustment to take place and thereby achieve alignment of the sash or the operator installation if required. For example, it permits the sash to be realigned if it is out of square after it has been installed without having to relocate the operator.

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Similarly if the operator itself has been installed incorrectly there is some adjustment available to rectify this.

5 As shown in Figure 11 the operator also includes a screw fixing placement insert 73. This insert 73 has two pairs of openings 74 which align with elongate openings 21a in the land 20. As shown in Figure 12 a series of inserts A-E are provided and a selected one of these can be located and
10 locked into the forward part 20 of the operator. In the preferred form inserts B-E are reversible and provide a discrete line of fixing by providing a countersink for a countersunk screw to locate in. The increments of these lines of fixing are depicted in Figure 13 and it will be seen
15 that insert A is non-reversible and provides a single discrete line of fixing as shown.

The common method of fixing a casement operator to a frame is to have single dedicated screw holes cast into the base 20 and thereby provide for one or two discrete lines of fixing. If these lines of fixing are not suitable for a particular application then either a new operator has to be made with fixings in the desired place or the fixing method is compromised. It is, however, a requirement to provide
25 fixings from 16mm to 32mm out from the internal vertical face of the frame section. This can be achieved using inserts as shown in Figure 12 which provide increments of fixing lines.

This means that end user requirements for fixing can be met
30 with a single operator fitted with the appropriate screw insert A-E. The screw inserts A-E are of a plastic moulding thus cheap to produce and do not represent a significant capital outlay for inventory as opposed to dedicated operators for discrete fixing requirements which do represent
35 a large capital outlay for inventory. Use of the screw inserts thus provides greater versatility for fixing of the operator.

CLAIMS

1. A rotary window operator which includes a rotatable handle (14) drivingly coupled to a link member (16) such that movement of the link member to effect opening and closing the window is achieved by rotation of the handle, the handle being moveable into a non-use position whereupon coupling means (29 and 30) provide the drive coupling between the handle and the link member is disconnected, the coupling means permitting the handle to be moveable into the non-use position at any angular disposition of the handle.
2. A rotary window operator as claimed in claim 1 wherein the coupling means includes a first drive member (29) coupled with said handle (14) and a second drive member (30) coupled to a drive shaft (19), said first and second drive members being rotatable relative to one another, said first and second drive members each including a plurality of teeth (34 and 35) which come into meshing engagement upon the handle being moved to an in-use position.
3. A rotary window operator as claimed in claim 2 wherein the first drive member is formed by a cage (29) to which the handle (14) is pivotally coupled, said second drive member being formed by a bush (30) located for axial movement within the cage, said teeth (34 and 35) being formed on opposing surfaces of the bush and cage, said drive shaft (19) extending through said cage and engaged within said bush.
4. A rotary window operator as claimed in claim 3 wherein biasing means (31) bias the bush to a position where the respective teeth (34 and 35) are disengaged.
5. A rotary window operator as claimed in claim 4 further including cam means (25a) which upon the handle (14) moving from a non-use position to an in-use position forces the bush (30) to move against the biasing means (31) whereupon the teeth (35) of the bush and the teeth (34) of cage (29) mesh.

6. A rotary window operator as claimed in claim 5 wherein the handle (14) is pivotally coupled between flanges (27) of the cage (29), said handle incorporating a cam surface (25a) 5 which is engaged with a pressure surface (30a) of the bush (30).

7. A rotary window operator as claimed in claim 6 wherein there is an inter-engagement between the handle (16) and an 10 adjacent flange (27) by a pin slidingly engaged in an arcuate slot of a width slightly less than the greatest cross sectional dimension of the pin, said slot being expandable as the pin is slid therealong, the ends of the slot respectively corresponding with the handle when in the in-use and non-use 15 positions.

8. A rotary window operator as claimed in any one of the preceding claims wherein the drive coupling between the handle (14) and the link member (16) includes a gear wheel 20 (18) carried by the link member, said link member having a plurality of lugs (37) formed integrally with the link member (16) and engaging in spaced openings (38) in the gear wheel.

9. A rotary window operator as claimed in claim 8 wherein 25 the link member (16) and gear wheel (18) are further interconnected by a boss (36) carried by one of said gear or link member and engaging in an opening (36a) in the respective other of the gear wheel and link member, a pivot pin engaging through the boss to provide a pivotal mounting of the link 30 member.

10. A rotary window operator as claimed in claim 9 wherein the said openings (38) in the gear wheel (18) are countersunk and the lugs (37) are swaged outwardly into the countersunk 35 areas to capture the gear wheel on the link arm (16).

11. A rotary window operator as claimed in any one of claims 7 to 10 wherein the link member (16) is formed of stainless

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steel and the gear wheel (18) is of sintered material or machined from free machining mild steel.

12. A rotary window operator as claimed in any one of the 5 preceding claims wherein the link member (16) projects from a housing (10), said handle (14) being rotatably mounted with a cover (11) of said housing, there being a mounting frame (15) which projects from the housing adjacent the link member (16).

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13. A rotary window operator as claimed in claim 12 wherein the mounting frame (15) includes a land (20) over which the link member (16) moves upon rotation of the handle (14), located to the opposite side of the link member is a bridge 15 (22) which is immediately adjacent to the link member.

14. A rotary window operator as claimed in claim 12 or 13 wherein the mounting frame (15) includes clamping means (43) for applying a clamping force to a portion of a window frame 20 (F) through which the mounting frame has been located, the window frame portion being located between the clamping means and a part (41) of the housing (10) of the operator.

15. A rotary window operator as claimed in claim 14 wherein 25 the clamping means includes a pocket (57) in the mounting frame (15) in which a clamping member (43) is located in a first orientation which permits the mounting frame to be engaged through an opening formed in a window frame (F), said clamping member (43) including an opening through which a 30 fastener (44) threaded into the operator housing (10) can locate in an interference fit whereby rotation of the fastener (44) causes the clamping member (43) to move within the pocket (57) from its first orientation to a second orientation for clamping engagement against a portion of the 35 window frame (F).

16. A rotary window operator as claimed in claim 15 wherein the mounting frame (15) includes a projection (47) which is

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engageable with the clamping member (43) to locate the clamping member in the second orientation upon rotation of the threaded fastener (44), there being a guide (48) for guiding movement of the clamping member upon further rotation 5 of the fastener.

17. A rotary window operator as claimed in any one of claims 12 to 16 further including a packer element (58) locatable between the mounting frame (15) and a second portion of the 10 window frame (F), said second window frame portion being located in a plane transverse to that part of the frame having the opening for the mounting frame of the operator.

18. A rotary window operator as claimed in any one of the 15 preceding claims further including an adjustable connection (61) to facilitate mounting of a window sash to a link arm (62) pivotally coupled (63) to the link member (16), said connection comprising a base (64) pivotally coupled to the end of the link arm and a bracket (66) attachable to the 20 sash, the position of the bracket on the base being adjustable without removal of the sash from the bracket.

19. A rotary window operator as claimed in claim 18 wherein 25 the base (64) is coupled to the sash via fastenings passing through elongate openings (72) in the base and aligned openings (68) in the bracket (66), there being a further fastening passing through a hollow pivot (65) coupling the base to the link arm (62) to the sash via an elongate opening (69) in the bracket.

30 20. A rotary window operator as claimed in claim 18 or 19 wherein the bracket (66) is formed with serrations or teeth (71) which inter-engage with corresponding serrations or teeth (70) of the base (64).

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21. A rotary window operator as claimed in claim 12 wherein the land (20) includes elongate openings (21a) through which fasteners can engage to fasten the mounting frame (15) to a

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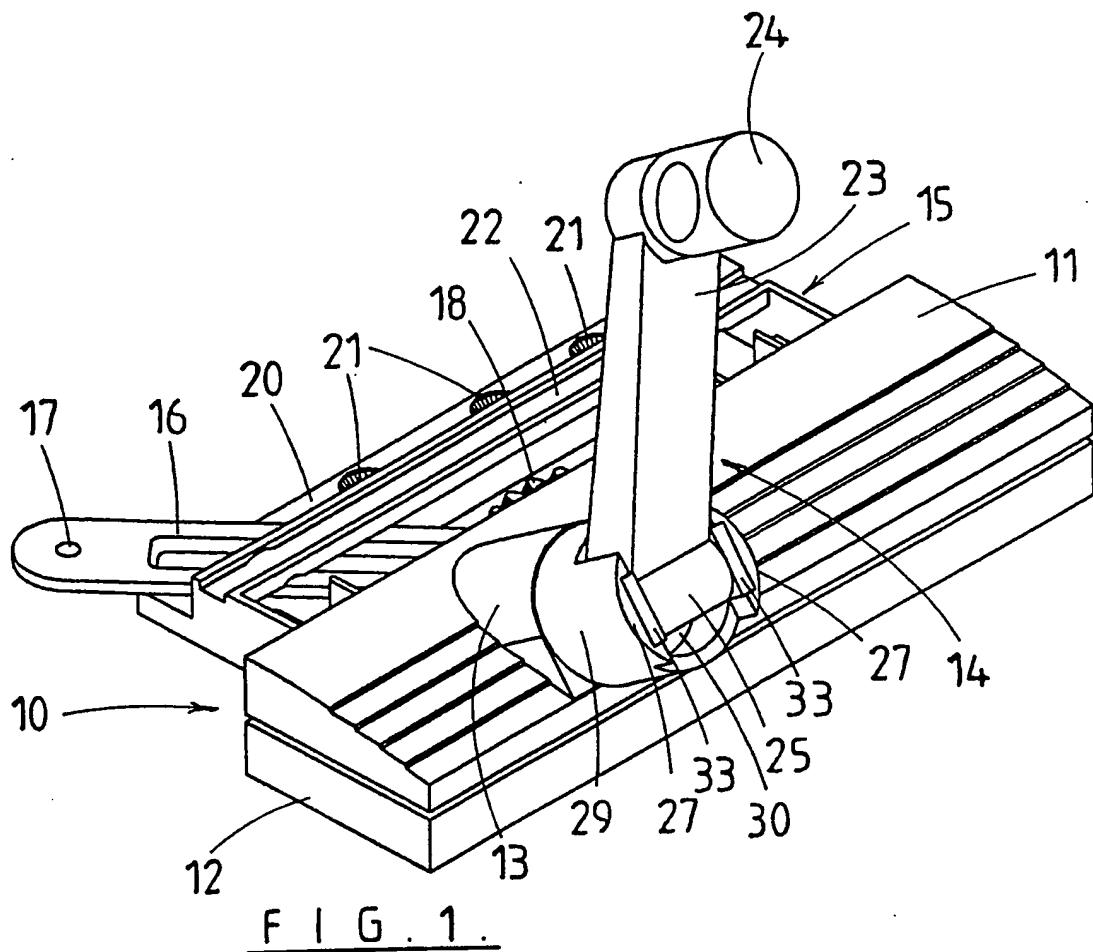
window frame (F), there being a fixing placement insert (73) located on the land, said insert having openings (74) which determine the positioning of the mounting fasteners and through which the fasteners can be engaged.

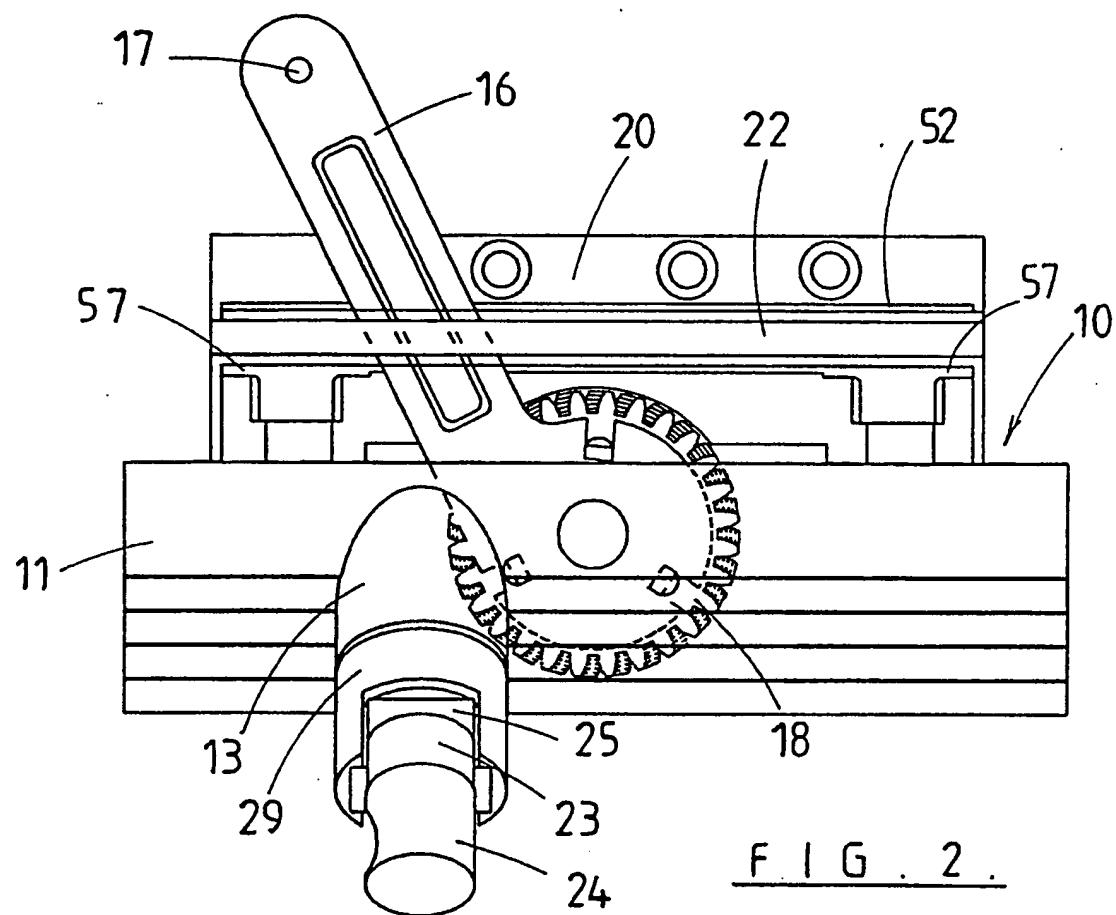
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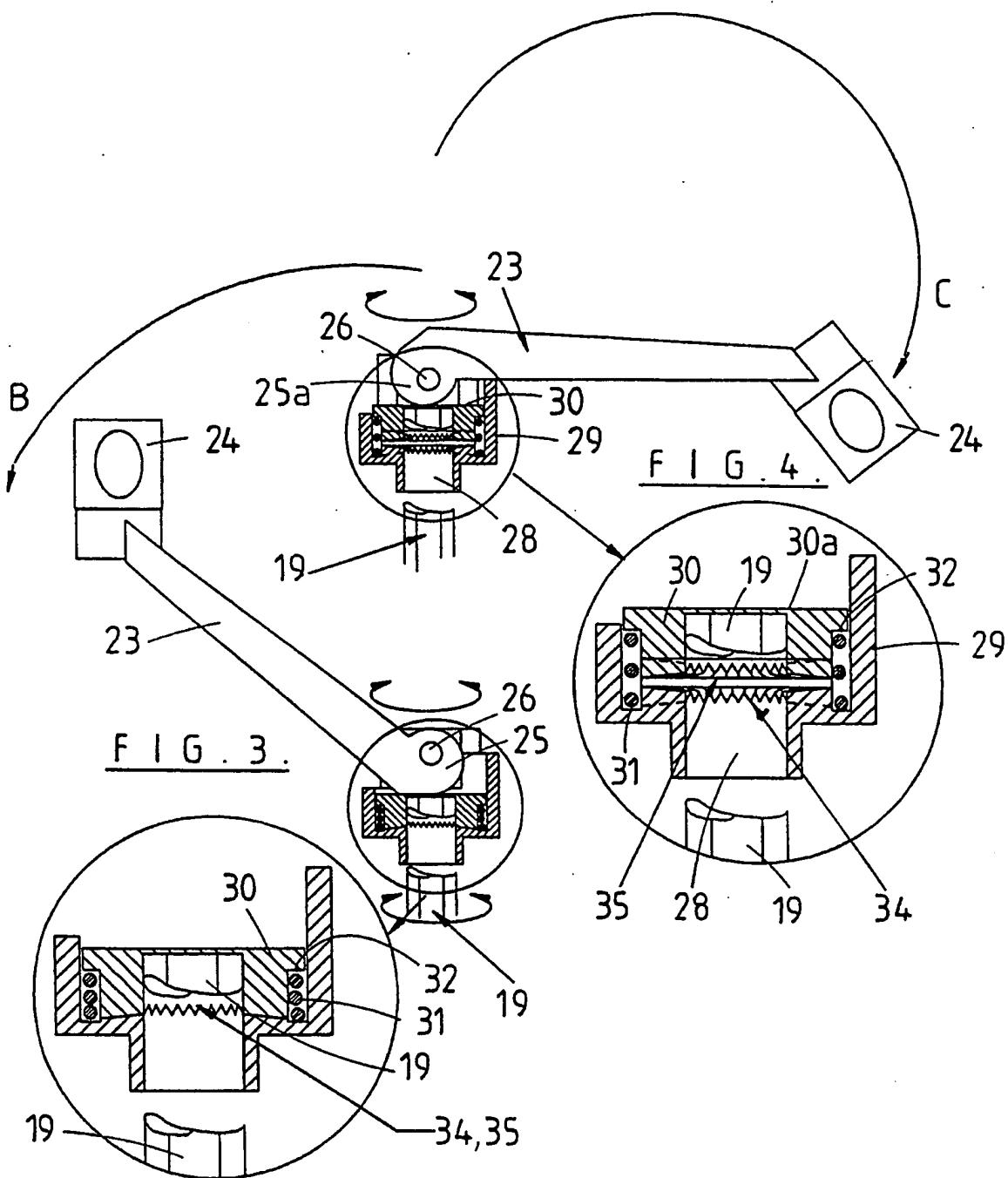
22. A rotary window operator as claimed in claim 21 wherein the openings (74) in the placement insert (73) are countersunk to accommodate the head of the fastening engaged therein.

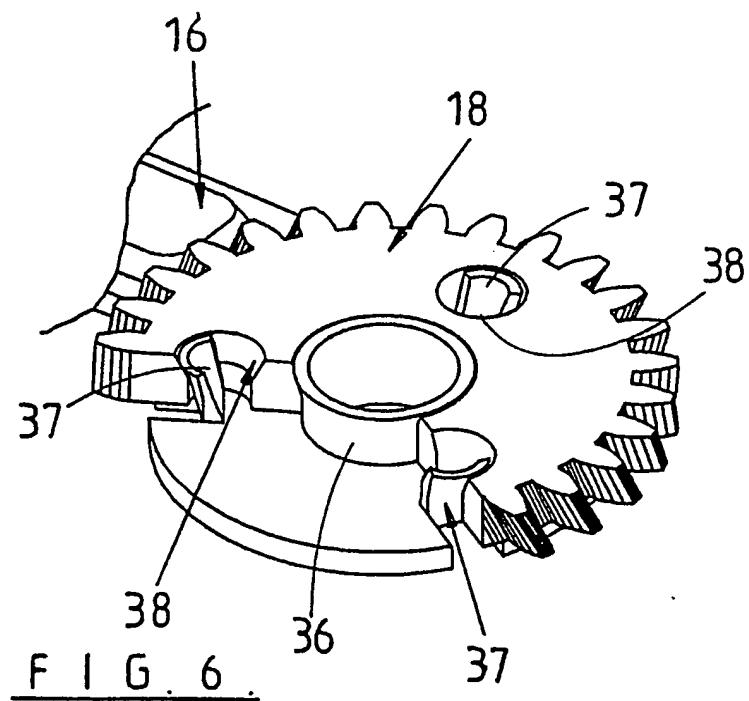
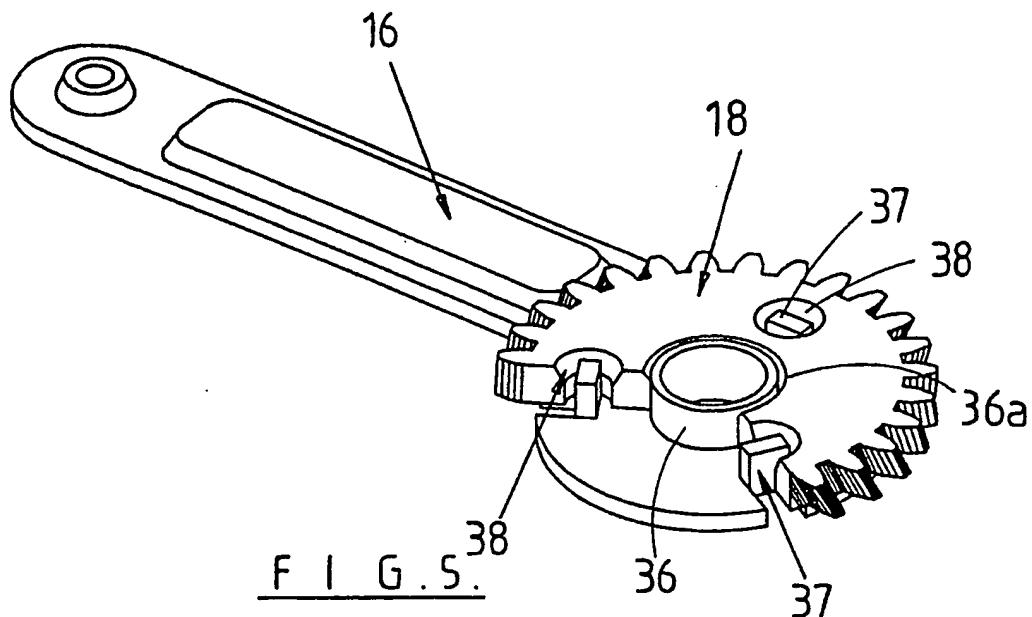
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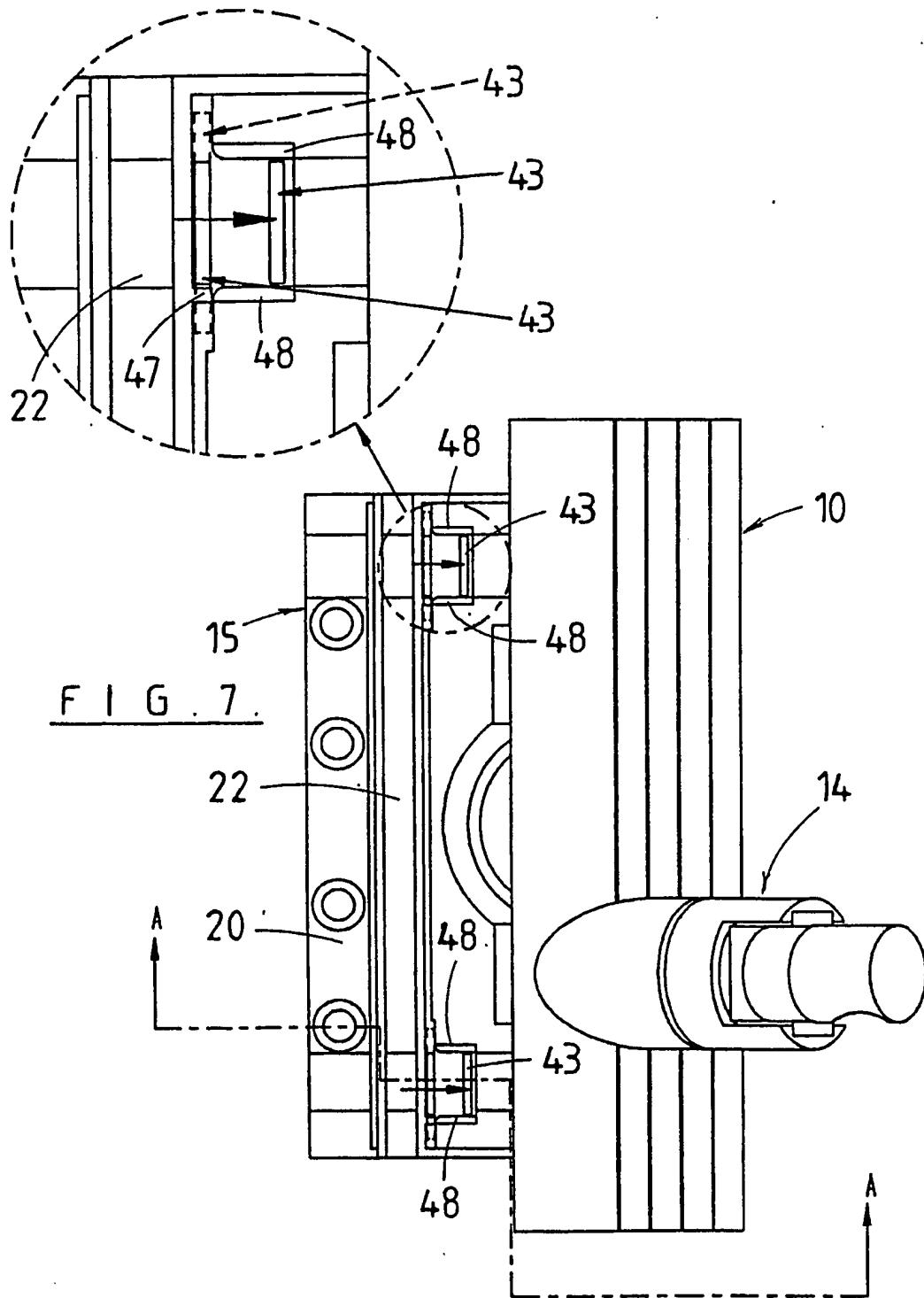
23. A rotary window operator as claimed in claim 21 or 22 wherein the placement insert (73) is formed of a plastics material.

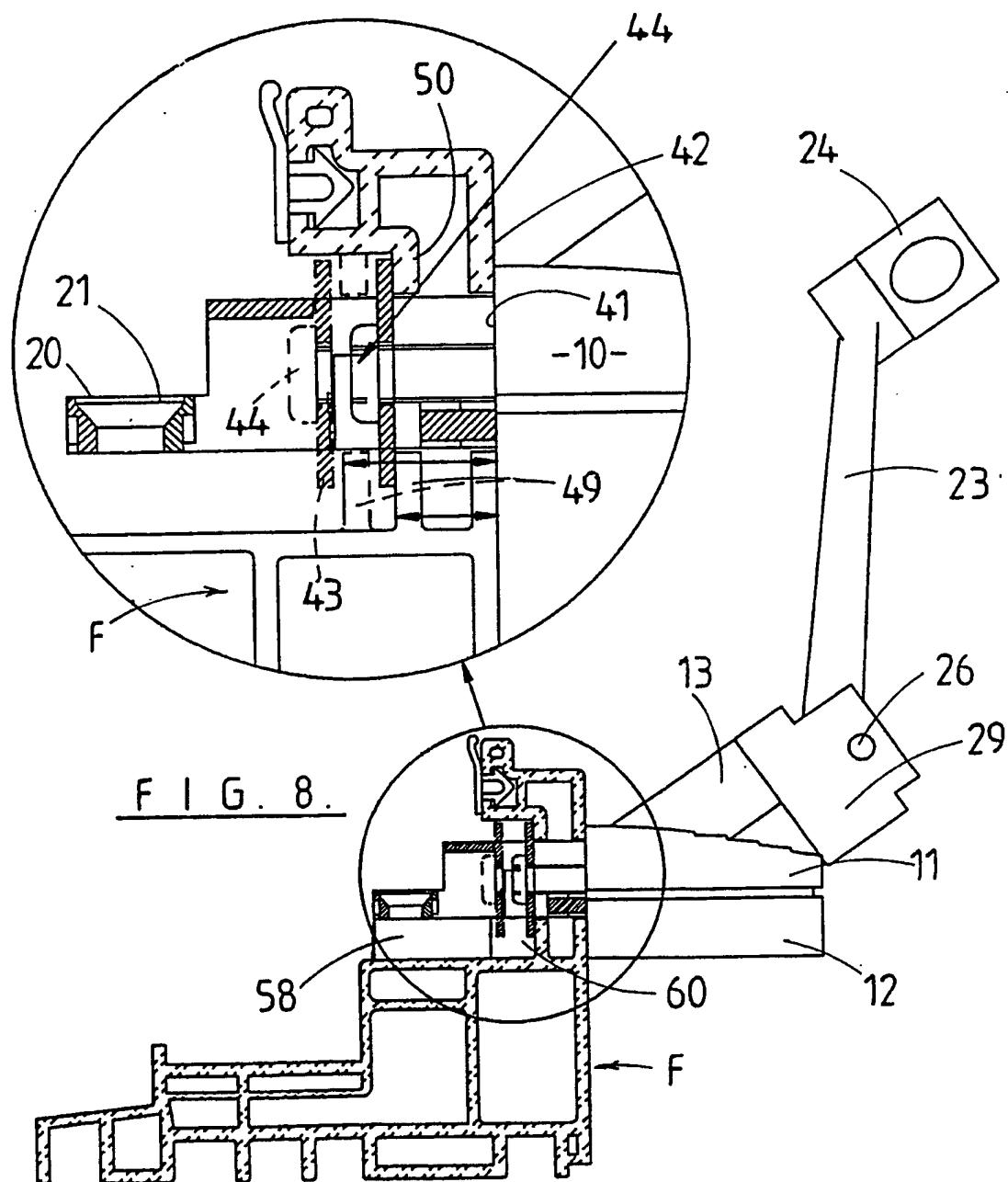


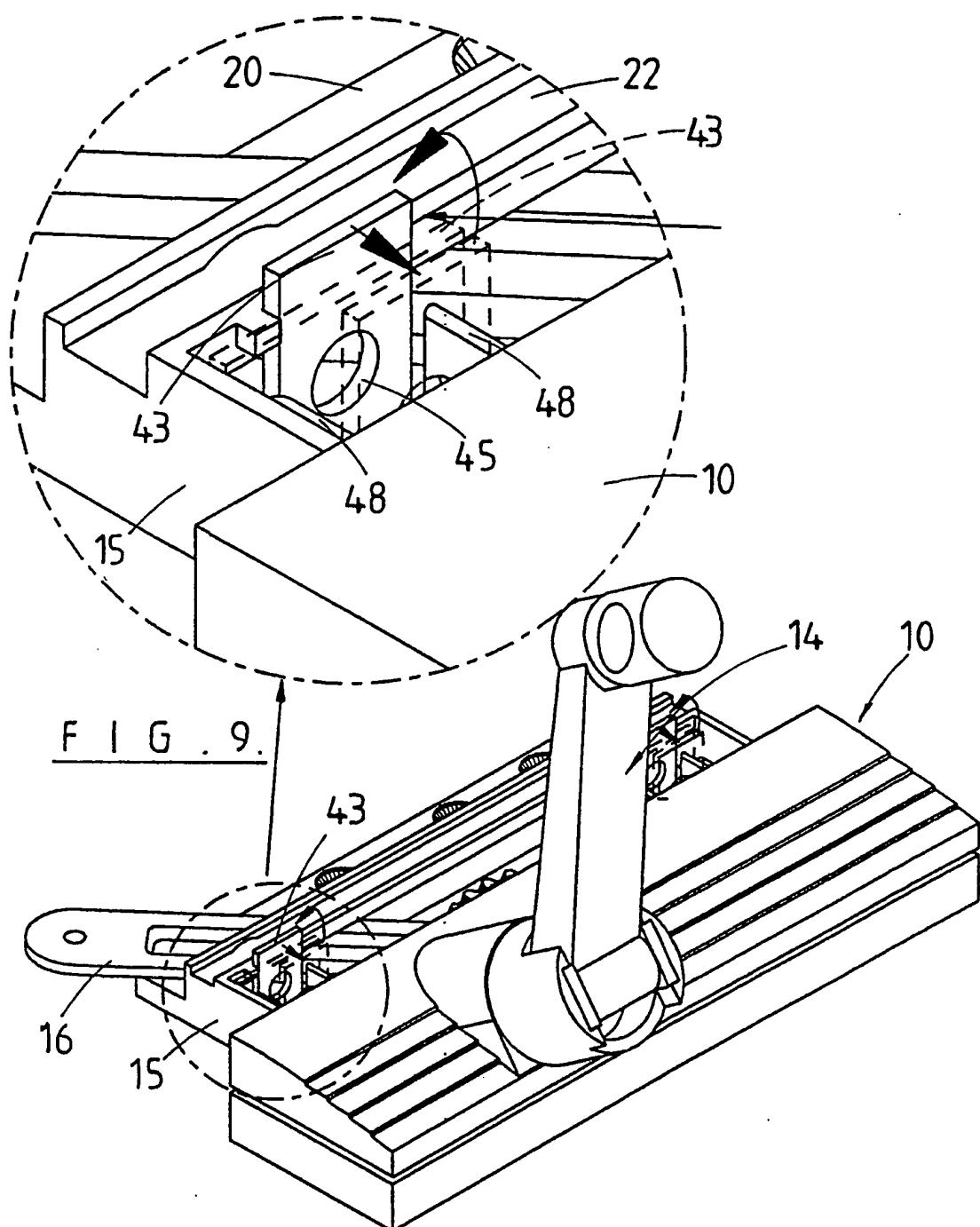




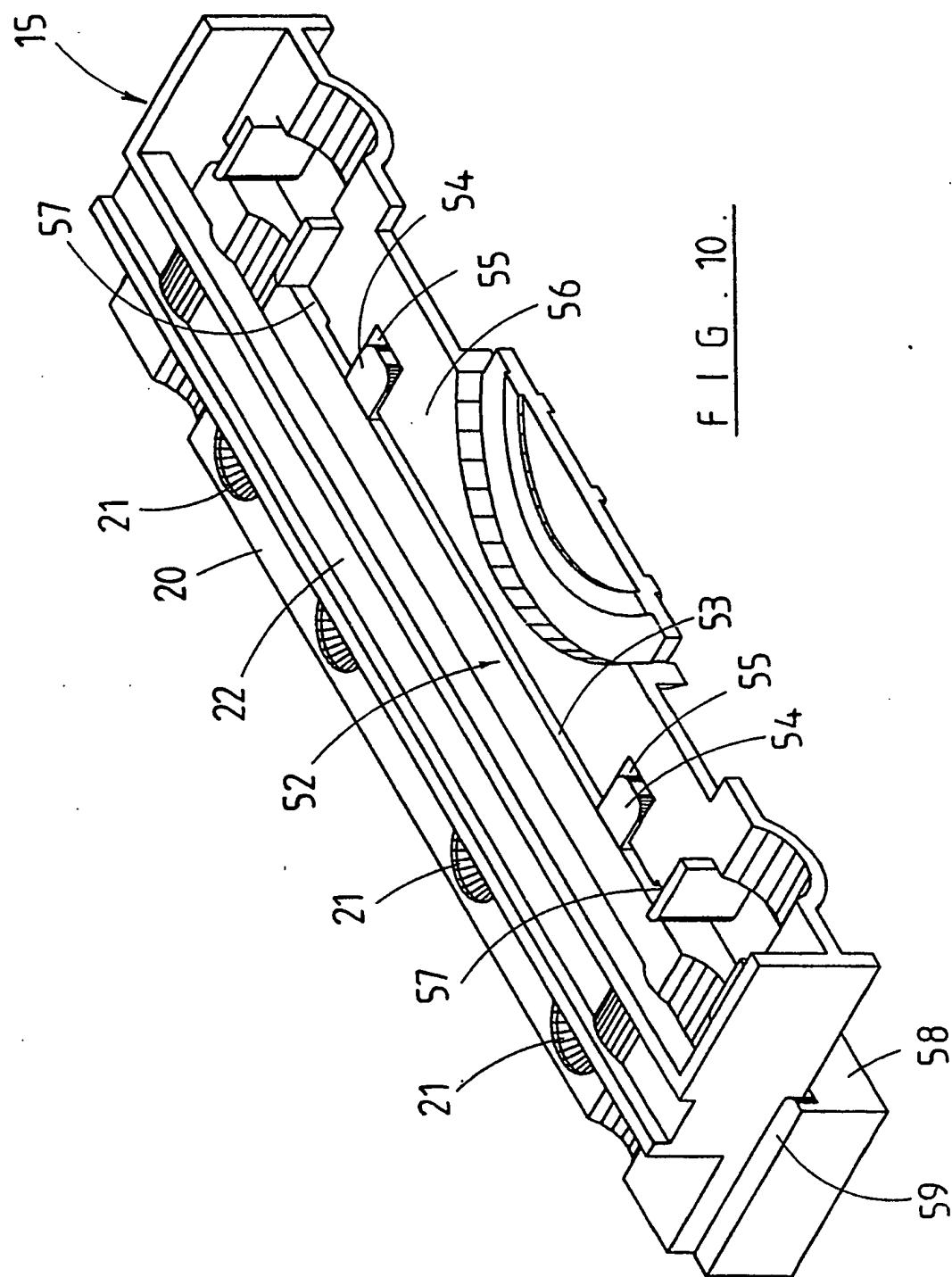




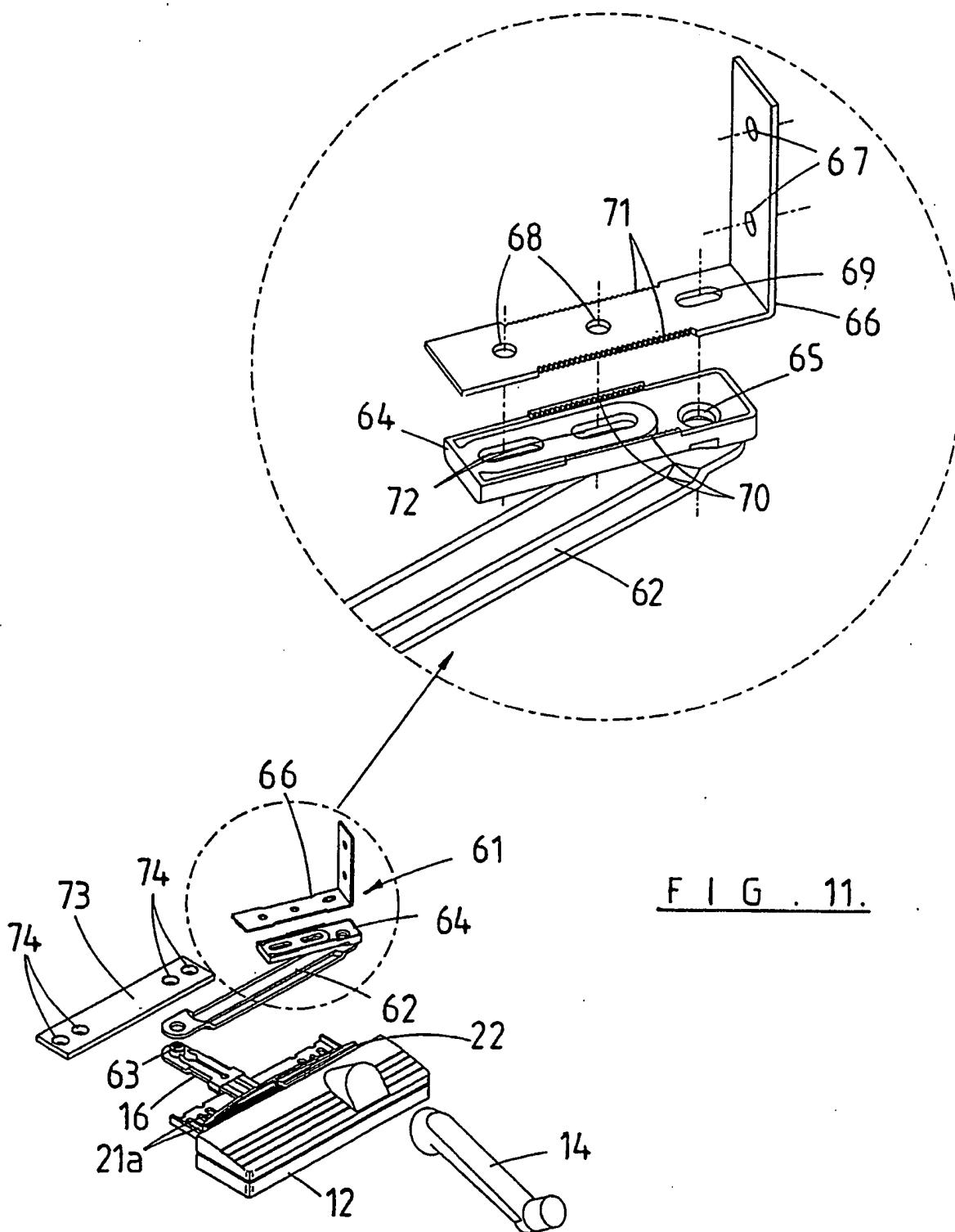




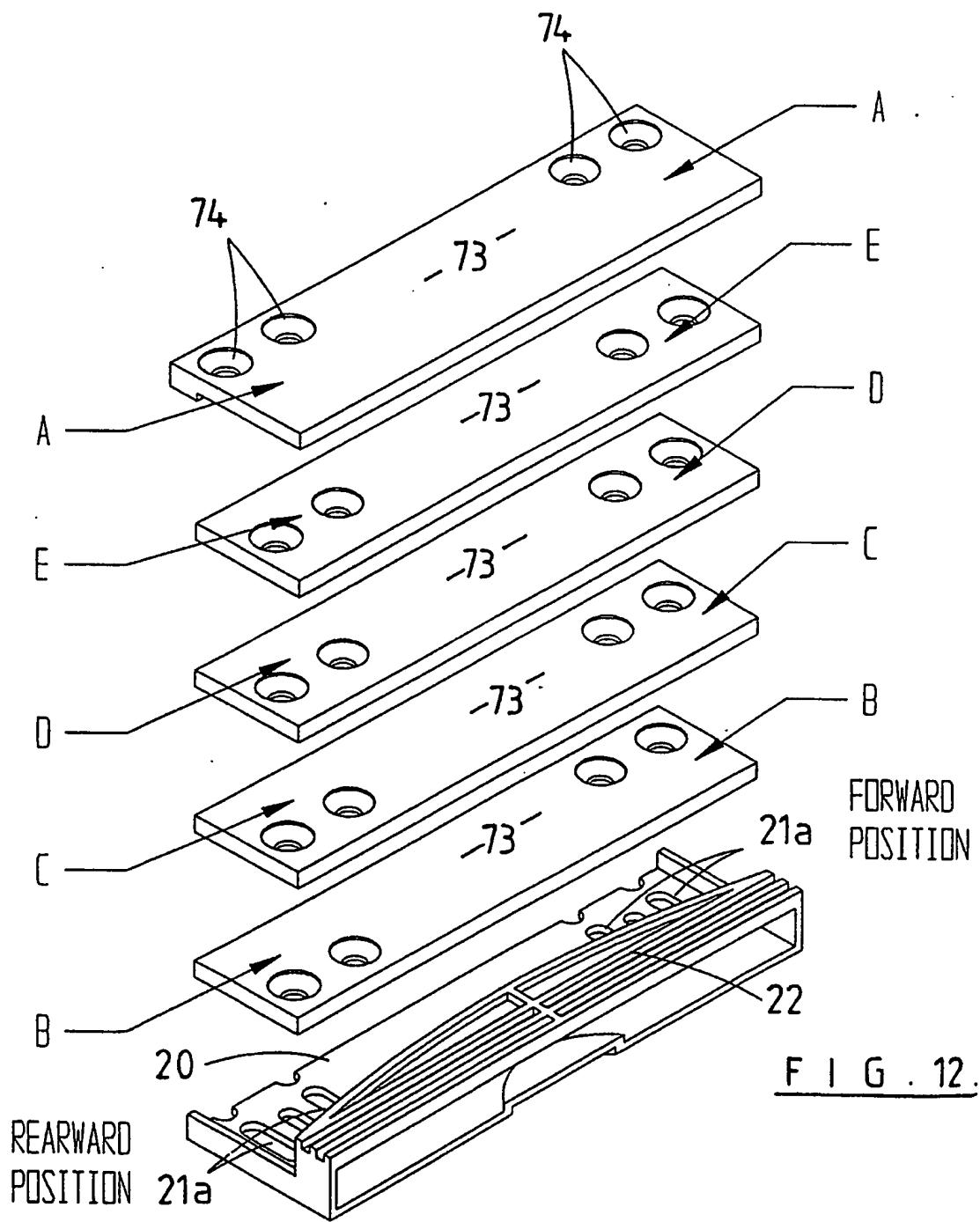
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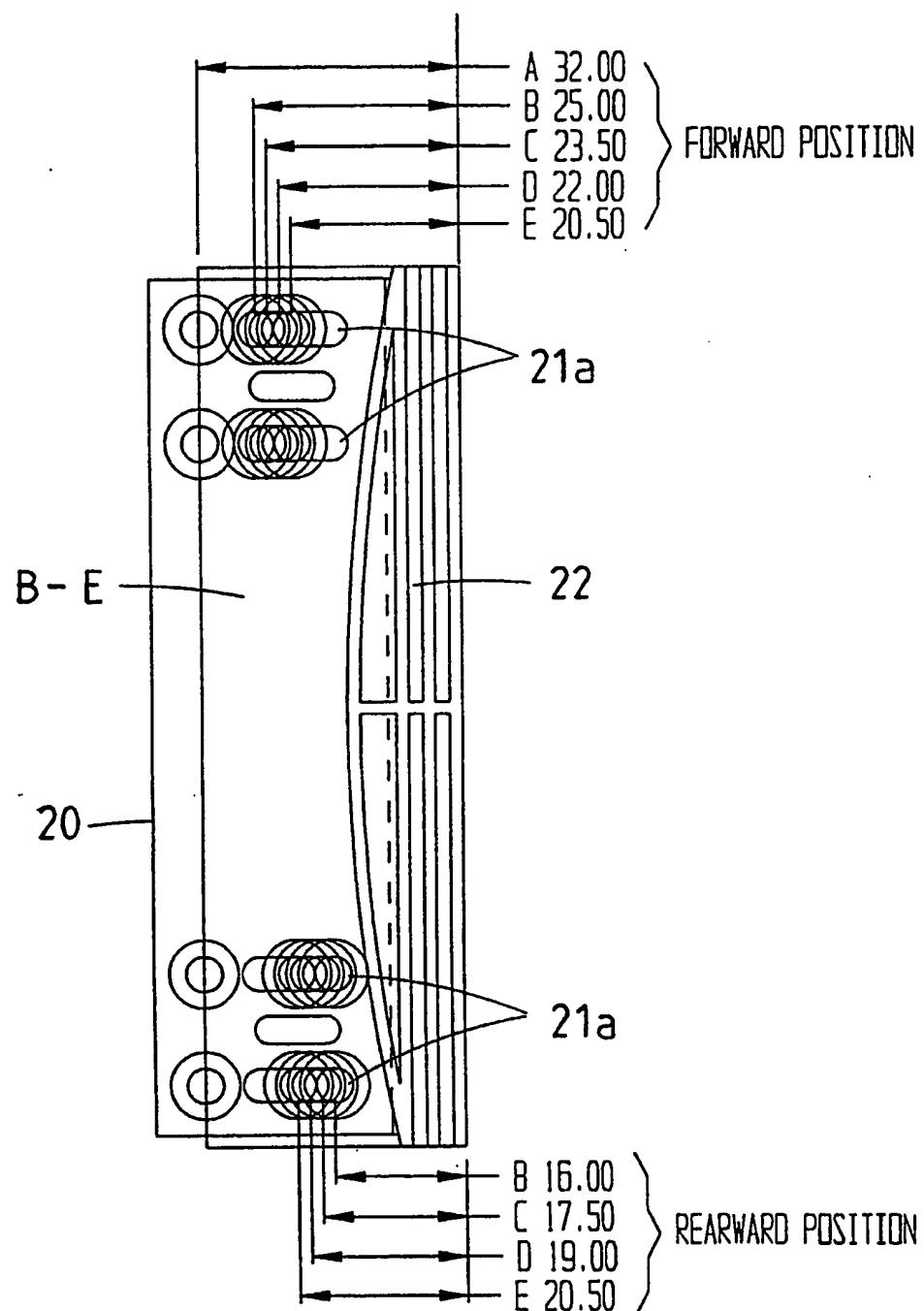
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INTERNATIONAL SEARCH REPORT

International application No.
PCT/NZ 94/00150

A. CLASSIFICATION OF SUBJECT MATTER

Int. Cl.⁶ E05F 11/10, 11/34

According to International Patent Classification (IPC) or to both national classification and IPC

B. FIELDS SEARCHED

Minimum documentation searched (classification system followed by classification symbols)

IPC: E05F 11/10, 11/34

Documentation searched other than minimum documentation to the extent that such documents are included in the fields searched
IPC: AU as above

Electronic data base consulted during the international search (name of data base, and where practicable, search terms used)

C. DOCUMENTS CONSIDERED TO BE RELEVANT

Category*	Citation of document, with indication, where appropriate, of the relevant passages	Relevant to Claim No.
X	AU, 84061/82A (OGDEN INDUSTRIES PTY LTD) 02 December 1982 Figure 1,2	1-2
A		3-23
X	AU, 38348/78A (WHITCO PTY LTD), 03 January 1980 Figures	1-2
A		3-23
X	AU, 58915/65A (GRAND), 16 November 1967 Figures 2,3	1-2,8,11 3-7,9,10,12-23
A		

Further documents are listed
in the continuation of Box C.

See patent family annex.

* Special categories of cited documents :	"T"	later document published after the international filing date or priority date and not in conflict with the application but cited to understand the principle of theory underlying the invention
"A" document defining the general state of the art which is not considered to be of particular relevance	"X"	document of particular relevance; the claimed invention cannot be considered novel or cannot be considered to involve an inventive step when the document is taken alone
"E" earlier document but published on or after the international filing date	"Y"	document of particular relevance; the claimed invention cannot be considered to involve an inventive step when the document is combined with one or more other such documents, such combination being obvious to a person skilled in the art
"L" document which may throw doubts on priority claim(s) or which is cited to establish the publication date of another citation or other special reason (as specified)	"&"	document member of the same patent family
"O" document referring to an oral disclosure, use, exhibition or other means		
"P" document published prior to the international filing date but later than the priority date claimed		

Date of the actual completion of the international search 3 May 1995	Date of mailing of the international search report 8 JUNE 1995 (08.06.95)
Name and mailing address of the ISA/AU AUSTRALIAN INDUSTRIAL PROPERTY ORGANISATION PO BOX 200 WODEN ACT 2606 AUSTRALIA Facsimile No. 06 2853929	Authorized officer G.B. Nath Telephone No. (06) 2832126

INTERNATIONAL SEARCH REPORTInternational application No.
PCT/NZ 94/00150

C(Continuation). DOCUMENTS CONSIDERED TO BE RELEVANT		
Category*	Citation of document, with indication, where appropriate of the relevant passages	Relevant to Claim No.
X	AU, 40808/72B (465073) (MEYERS TAYLOR PTY LTD) 11 October 1973	1-2
A		3-23
Y	GB, 529018A (THE CRITTALL MANUFACTURING COMPANY LIMITED), 12 November 1940	1-2
A	Figure 1	3-23
Y	US, 2219362A (HAGSTROM), 29 October 1940	1-2
A	Figures	3-23
A	GB, 2247279A (DAVIS), 26 February 1992	1-23
A	Figures	1-23
A	US, 2636727A (TOTH), 28 April 1953	1-23
A	Figures	1-23
A	US, 2545449A (CURLEY), 20 March 1951	1-23
A	Figures	1-23
Y	AU, 24860/62B (274157) (SEACOMB INDUSTRIES PTY LTD)	1-2
A	Figures	3-23

INTERNATIONAL SEARCH REPORT

Information on patent family members

International application No.
PCT/NZ 94/00150

This Annex lists the known "A" publication level patent family members relating to the patent documents cited in the above-mentioned international search report. The Australian Patent Office is in no way liable for these particulars which are merely given for the purpose of information.

Patent Document
Cited in Search
Report

Patent Family Member

GB 2247279 AU 81304/91 NZ 234642

END OF ANNEX